

UNITED NATIONS GLOBAL GEODETIC CENTRE OF EXCELLENCE

MODERNISING GEOSPATIAL REFERENCE SYSTEM CAPACITY DEVELOPMENT WORKSHOP

Height datums and geoid models

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Height is hard ... but important

- Which way does water flow?
- What is at risk during a flood?
- How do we build a sewerage system in the city?
- How to develop an efficient irrigation system for agriculture?
- How to ensure the correct inclination of railways and roads?
- How to know the under keel clearance of a ship?
- How to monitor the sea level change?
- What is the height of the top of the mountain?



https://www.welt.de/vermischtes/weltgeschehen/gallery9348988/Das-Jahrzehnt-der-Wetterkatastrophen.html





Introduction to height

- Traditionally, people want to know the height of something with respect to sea level.
 - These are known as "physical heights"
- Satellite positioning systems (GNSS and remote sensing) determine heights relative to the ellipsoid.
 - These are known as "geometric heights"
- It is important to understand how these systems are different and how data from these systems can be used together.





Physical vs Geometric heights



- Not physically meaningful
- Used by GNSS
- Water doesn't always flow downhill



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Heights referring to mean sea level

- Levelled heights (often) refer to the mean sea level determined at selected tide gauges.
- The sea surface is not always the same height above the geoid, it varies due to ocean currents, water temperature and salinity.
- The mean sea level may be closer to or farther from the equilibrium figure of the Earth (geoid) depending on the geographical location.
- Thus, the zero elevation as defined by one country (or region) differs up to ±2 metres from the zero elevation as defined by other countries.
 0' 30' 60' 90' 120' 150' 180' -150' -120' -90' -60' -30' 0'



Height datum referenced to tide gauge



The Geoid





Scale exaggerated to make the difference visible. In reality ±150 m.







Geometric vs Physical height

- Different techniques are used to determine heights.
- However, there is no guarantee that each technique will produce the same height.
- Heights determined with GNSS do not refer to the mean sea surface, but to the ellipsoid (a geometry model of the Earth).
- Differences between GNSS heights and those referring to the mean sea surface may reach up to ±100 m.



Creating a geoid model

Gravity measurements



Physical datums

- The determination of the gravitational potential at any point requires gravity anomalies all over the Earth.
 - The long wavelength contribution N_G is provided by a set of spherical harmonic coefficients (geopotential or global gravity model);
 - The middle wavelength contribution N_L is estimated from the local anomalies (terrestrial, marine or airborne gravity in the area of study)
 - The short wavelength contribution N_T is computed by using a digital terrain model (topographic heights)
 - The geoid undulation (or height anomaly) is given by
 N = N_G + N_L + N_T



GRACE satellite: http://geoid.colorado.edu/grace/ GOCE satellite: https://gisgeography.com/earth-satellite-list/

Global geoid model (EGM2008)

Example of a global geoid – EGM2008 - Resolution: 5' x 5'



Global geoid model (EGM2008)

- Models like the Earth Geopotential Model 2008 are a combination of space, air, ship and terrestrial gravity and can form the basis of a country height datum.
- The amount of data from different regions in EGM2008 is not the same.
- In some cases, countries have added to EGM2008 models with extra gravity data to improve the accuracy of the model.





Global geoid model (EGM2008)

EGM2008 uncertainty



Other global gravity models



https://icgem.gfz-potsdam.de/tom_longtime



Global Gravity Field Models

We kindly ask the authors of the models to check the links to the original websites of the models from time to time. Please let us know if something has changed.

The table can be interactively re-sorted by clicking on the column header fields (Nr, Model, Year, Degree, Data, Reference). In the data column, the datasets used in the development of the models are summarized, where **A** is for altimetry, **S** is for satellite (e.g., GRACE, GOCE, LAGEOS), **G** for ground data (e.g., terrestrial, shipborne and airborne measurements) and **T** is

The links calculate and show in the last columns of the table directly invoke the Calculation Service and Visualization page for the selected model. For models with a registered doi ("digital object identifier") the last column contains the symbol \checkmark , which directly opens the page on "http://dx.doi.org/". If you click on the reference, the complete list of references can be seen.

Nr	Model	Year	Degree	Data	References	
180	WHU-SWPU-GOGR2022S	2023	300	S (Goce), S (Grace)	Zhao, Yongqi et al 2023	
179	GOSG02S	2023	300	S (Goce)	Xu, Xinyu et al 2023	
178	Tongji-GMMG2021S	2022	300	S (Goce), S (Grace)	Chen, J. et al, 2022	
177	SGG-UGM-2	2020	2190	A, EGM2008, S(Goce), S(Grace)	Liang, W. et al, 2020	
176	XGM2019e_2159	2019	2190 5540 760	A, G, S(GOCO06s), T	Zingerle, P. et al, 2019	
175	GO_CONS_GCF_2_TIM_R6e	2019	300	G (Polar), S(Goce)	Zingerle, P. et al, 2019	
174	ITSG-Grace2018s	2019	200	S(Grace)	Mayer-Gürr, T. et al, 2018	
173	EIGEN-GRGS.RL04.MEAN-FIELD	2019	300	S	Lemoine, J.M. et al, 2019	
172	GOC006s	2019	300	S	Kvas, A. et al, 2021	
171	GO_CONS_GCF_2_TIM_R6	2019	300	S(Goce)	Brockmann, J. M. et al, 2021	
170	GO_CONS_GCF_2_DIR_R6	2019	300	S	Bruinsma, S. L. et al, 2014	
169	IGGT_R1C	2018	240	G, S(Goce), S(Grace)	Lu, B. et al., 2019	
168	Tongji-Grace02k	2018	180	S(Grace)	Chen, Q. et al, 2018	
167	SGG-UGM-1	2018	2159	EGM2008, S(Goce)	Liang, W. et al., 2018 & Xu, X. et al. (2017)	
166	GOSG01S	2018	220	S(Goce)	Xu, X. et al., 2018	
165	IGGT_R1	2017	240	S(Goce)	Lu, B. et al, 2017	
164	IfE_GOCE05s	2017	250	S	Wu, H. et al, 2017	
163	GO_CONS_GCF_2_SPW_R5	2017	330	S(Goce)	Gatti, A. et al, 2016	
162	GAO2012	2012	360	A, G, S(Goce), S(Grace)	Demianov, G. et al, 2012	
161	XGM2016	2017	719	A, G, S(GOCO05s)	Pail, R. et al, 2017	
160	Tongji-Grace02s	2017	180	S(Grace)	Chen, Q. et al, 2016	
159	NULP-02s	2017	250	S(Goce)	A.N. Marchenko et al, 2016	
158	HUST-Grace2016s	2016	160	S(Grace)	Zhou, H. et al, 2016	
157	ITU_GRACE16	2016	180	S(Grace)	Akyilmaz, O. et al, 2016	

Airborne gravity

Measures the total vertical acceleration. Need highly accurate GPS data and IMU to remove of the effect of the aircraft motion to recover a gravity signal.

Benefits of airborne gravity observations

- Easy to obtain consistent coverage over otherwise inaccessible areas (mountains, shallow coastal regions)
- Covers large areas quickly and cheaply compared to terrestrial methods.
- ✓ Can cover the littoral zone easily where there are large errors in satellite altimetry and terrestrial/Shipborne methods aren't practical.







Example of geoid model EGM2008+airborne(partial)+terrestrial

Australian Gravimetric Quasigeoid 2017 (AGQG2017)

AGQG2017 - Uncertainty



Regional scale geoid modelling



- Data augmentation procedure Regional gravity anomaly data are augmented with global gravity models to incorporate finer scale features (< 100 km and often up to $\pm 1 m$ variations) using the so-called "Remove-Compute-Restore" technique.
 - **Remove:** Long wavelength Global Gravity Model derived gravity anomalies are subtracted from the regional Gravity anomaly data to produce a residual ideally composed of only only high frequency signals.
 - **Compute:** The residual gravity anomalies are then transformed into residual geoid variations. This process can be undertaken in several ways (e.g. gridding the data and using FFT/Numerical Stokes integration or via statistical techniques such as Least Squares Collocation) and often includes low & high pass filtering (e.g. using modified Stokes kernels) to optimise the features determined from the regional scale residual gravity data.
 - **Restore:** The long wavelength global gravity models is then "restored" (added back) to the residual geoid model from the compute step to produce the final full spectrum model (generally gridded at 1 arc minute).

Height datum referenced to geoid model



Considerations for a geoid model based vertical datum

- Requires permanent operation of a CORS network with ample distribution of stations throughout your country.
- For much of the world, the datasets available to assess the quality of precise geoid models is scarce (high quality GNSS and levelling networks). Many countries also lack the gravity data required.
- The most popular technique to create the input gravity model is combination of satellite airborne and terrestrial data.
- The transition from any vertical datum to another should be accompanied by a transformation surface to allow traceability to the old standard.





Considerations for a geoid model based vertical datum

- You need a reliable GNSS CORS network
- You need a geoid model which is more accurate than your current levelling network
- Users need to be proficient in the use of GNSS to determine a local height network
- It may permit reassignment of ongoing maintenance costs of ground marks to be directed to gravity observations and geoid model
- Particularly relevant for big countries and / or countries with surface heave (e.g. colder)





USA and NZ geoid models

NZGeoid2016



Sauce: https://beta.ngs.noaa.gov/GEOID/xGEOID19/



Sauce: https://www.linz.govt.nz/data/geodeticsystem/datums-projections-and-heights/verticaldatums/new-zealand-quasigeoid-2016-nzgeoid2016

LSC workflow in GitHub

GeoscienceAustralia / analysis-ready-gravity-dat	a-workflow	Q Type 🕖 to search	+ - O II A				
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Darbeheshti news		3c0fa54 · 4 days ago 🛛 36 Commits	Analysis ready data for gravity observations is a set of Matlab files to				
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runPreparation	Add files via upload	2 months ago	Activity Custom properties Activity				
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	Create LICENSE	3 weeks ago	父 0 forks Report repository				
C README.md	Update README.md	2 weeks ago					
🗋 RunDemo.m	news	4 days ago	Releases				
다 README 최조 CC0-1.0 license			Create a new release				

AuScope

NCRIS

https://github.com/GeoscienceAustralia/analysis-ready-gravity-data-workflow

Corrector surface (h,H,N)

- Correction between a geoid model and a height datum implemented in a country.
- Model of bias, discrepancies and systematic effects in a height datum when it was realised or since it's realisation.
 - The residual errors $\varepsilon = h H N$ are modelled using a parametric model (corrector surface), which may be based on a simple bias, a bias and a tilt, higher order polynomials with different base functions, finite element models, Fourier series, or least squares collocation-based approaches.
 - The unknown parameters for the selected corrector surface are obtained via a common least-squares adjustment of ellipsoidal, orthometric and geoid height data over a network of co-located GNSS-levelling benchmarks.

Height datum referenced to geoid model + corrector surface



Differences between gravimetric and geometric quasigeoid at the 7224 GNSS-AHD stations on the mainland

- North-south tilt
- Regional biases
- Levelling errors

(d) 130" 140" 120 150* 110 -10 -10 -20: _20 -30 _30' ~40* _40' 130'140 120 150 110 0.5 (m) 0.4

Featherstone, W.E., McCubbine, J.C., Brown, N.J. *et al.* The first Australian gravimetric quasigeoid model with location-specific uncertainty estimates. *J Geod* **92**, 149–168 (2018). https://doi.org/10.1007/s00190-017-1053-7

Corrector surface (h,H,N)



Corrector surface (h,H,N)

Remarks:

- A well-distributed set of levelling points co-located with GNSS positioning is desired;
- The applicability of the corrector surface depends on the number and quality of the included points with co-located data (h, H, N);
- The more points the better the corrector surface;
- The better the geographic distribution of co-located data the better the corrector surface;
- GNSS points and levelling points of low order should not be included;
- The predicted data are the height uncertainties; the original data are not improved.

Two frame solution

